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# **LinMot®**

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Installation Documentation for the following Controllers:

- B1100-PP (-HC, -XC)
- B1100-VF (-HC, -XC)
- B1100-GP (-HC, -XC)

**RS 485**

**RS 232**

**CANopen**



**Easy Steps**

**±10V**

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## **Servo Controller Installation Guide**

Document version: 3.9.4 / June 2010

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**Note**

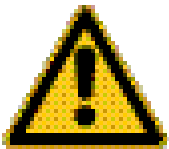
The information in this documentation reflects the stage of development at the time of press and is therefore without obligation.

NTI AG reserves itself the right to make changes at any time and without notice to reflect further technical advance or product improvement.

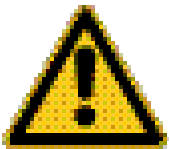
Document version 3.9.4 / Whp / May 2010

## **Table of Content**

<b>IMPORTANT NOTES FOR B1100 SERIES CONTROLLERS.....</b>	<b>4</b>
<b>SYSTEM OVERVIEW.....</b>	<b>5</b>
<b>B1100 INTERFACES.....</b>	<b>6</b>
<b>FUNCTIONALITY.....</b>	<b>7</b>
<b>SOFTWARE.....</b>	<b>7</b>
<b>POWER SUPPLY AND GROUNDING.....</b>	<b>8</b>
<b>DESCRIPTION OF THE CONNECTORS / INTERFACES.....</b>	<b>9</b>
<b>PHYSICAL DIMENSION.....</b>	<b>14</b>
<b>POWER SUPPLY REQUIREMENT.....</b>	<b>15</b>
<b>ORDERING INFORMATION.....</b>	<b>16</b>
<b>INTERNATIONAL CERTIFICATIONS.....</b>	<b>16</b>
<b>DECLARATION OF CONFORMITY CE-MARKING.....</b>	<b>17</b>
<b>CONTACT ADDRESSES.....</b>	<b>18</b>

**Important notes for B1100 series controllers****CAUTION!**

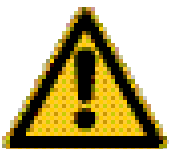
In order to assure a safe and error free operation, and to avoid severe damage to system components, all system components must be directly attached to a single ground bus that is earth or utility grounded (see chapter Power Supply and Grounding).



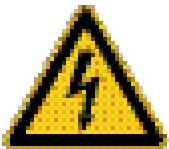
Each system component should be tied directly to the ground bus (star pattern), rather than daisy chaining from component to component. (LinMot motors are properly grounded through their power cables when connected to LinMot controllers) (see chapter Power Supply and Grounding).



All connectors must not be connected or disconnected while DC voltage is present. Do not disconnect system components until all LinMot controllers LEDs have turned off. (Capacitors in the power supply may not fully discharge for several minutes after input voltage has been disconnected). Failure to observe these precautions may result in severe damage to electronic components in LinMot motors and/or controllers.

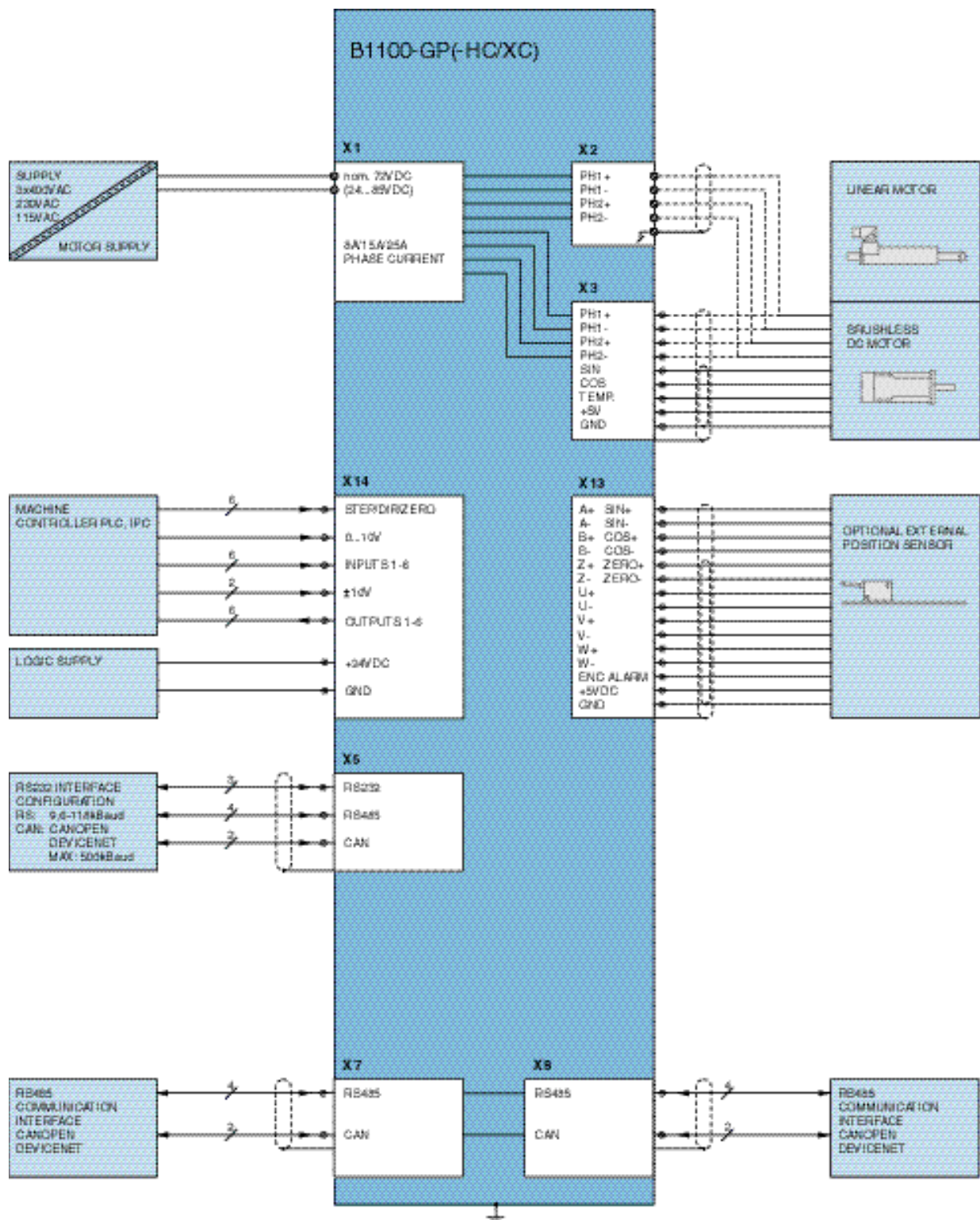


Do not switch Power Supply DC Voltage. All power supply switching and E-Stop breaks should be done to the AC supply voltage of the power supply.



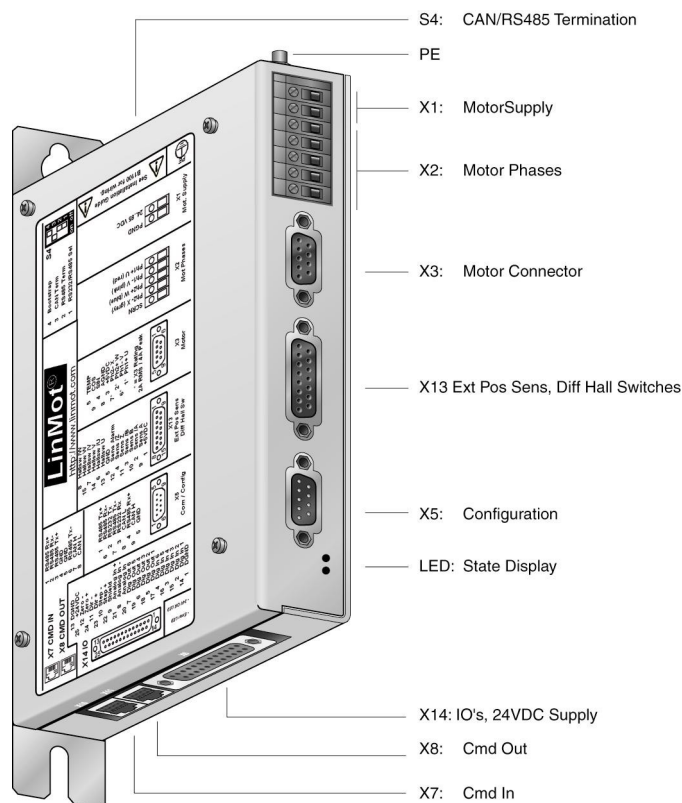
Do not connect or disconnect the motors from controllers with voltage present. Wait to connect or disconnect motors until all LinMot controllers LEDs have turned off. (Capacitors may not fully discharge for several minutes after power has been turned off). Failure to observe these precautions may result in severe damage to electronic components in LinMot motors and/or controllers.

## System Overview



Typical servo system B1100-XX-YY: Servo controller, motor and power supply.

### B1100 Interfaces



		B1100-PP /-HC/-XC	B1100-VF /-HC/-XC	B1100-GP /-HC/-XC
<b>Connector</b>				
X1	Motor Supply	•	•	•
X2	Motor Phases (Screw Terminals)	•	•	•
X3	Motor / Motor Signals	•	•	•
X5	Com / Config RS232, RS485, CAN	•	•	•
X7	RS485 / CAN In	•	•	•
X8	RS485 / CAN Out	•	•	•
X13	External/Simulated Position Encoder Diff Hall Switches	•	•	•
X14	6 Digital Inputs 6 Digital Outputs Analog In 0..10V Analog In -10V.. +10V Diff Step Dir zero 24V Logic Supply	•	•	•
LED	State Indicator	•	•	•
S4	Bus Termination	•	•	•

## Functionality

	B1100-PP	B1100-PP-HC	B1100-PP-XC	B1100-VF	B1100-VF-HC	B1100-VF-XC	B1100-GP	B1100-GP-HC	B1100-GP-XC
<b>Supply Voltage</b>									
Motor Supply 72VDC (24...85VDC)	•	•	•	•	•	•	•	•	•
Logic Supply 24VDC (22...26VDC)	•	•	•	•	•	•	•	•	•
<b>Motor Phase Current</b>									
8A <sub>peak</sub> / 6A <sub>rms</sub>	•			•			•		
15A <sub>peak</sub> / 9A <sub>rms</sub>		•			•			•	
25A <sub>peak</sub> / 12A <sub>rms</sub>			•			•			•
<b>Controllable Motors</b>									
LinMot P01-23x...	•	•	•	•	•	•	•	•	•
P01-37x...	•	•	•	•	•	•	•	•	•
P01-48x...	•	•	•	•	•	•	•	•	•
DC Motors	•	•	•	•	•	•	•	•	•
Brushless DC / EC Motors	•	•	•	•	•	•	•	•	•
<b>Command Interface</b>									
Easy Steps Max. 6 Commands	•	•	•	•	•	•	•	•	•
+/-10V Current Command Interface				•	•	•	•	•	•
Step Direction Indexer Interface				•	•	•	•	•	•
Cmd Tab IO Interface (X14-IOs) (with EasySteps)				•	•	•	•	•	•
RS232 up to 115.2 kBaud							•	•	•
RS485 up to 115.2 kBaud							•	•	•
CANOpen up to 1MBaud							•	•	•
DeviceNet 125, 250, 500 kBaud							•	•	•
<b>External Position Sensor</b>									
Incremental RS422 up to 2 MHz	•	•	•	•	•	•	•	•	•
<b>Position Indexer Input</b>									
Step Dir Zero/ ABZ RS422 up to 2 MHz				•	•	•	•	•	•
<b>Position Encoder Simulation</b>									
AB RS422 up to 2.5 MHz				•	•	•	•	•	•
<b>Configuration</b>									
RS232 Configuration	•	•	•	•	•	•	•	•	•
CAN Multi Axes Configuration	•	•	•	•	•	•	•	•	•

## Software

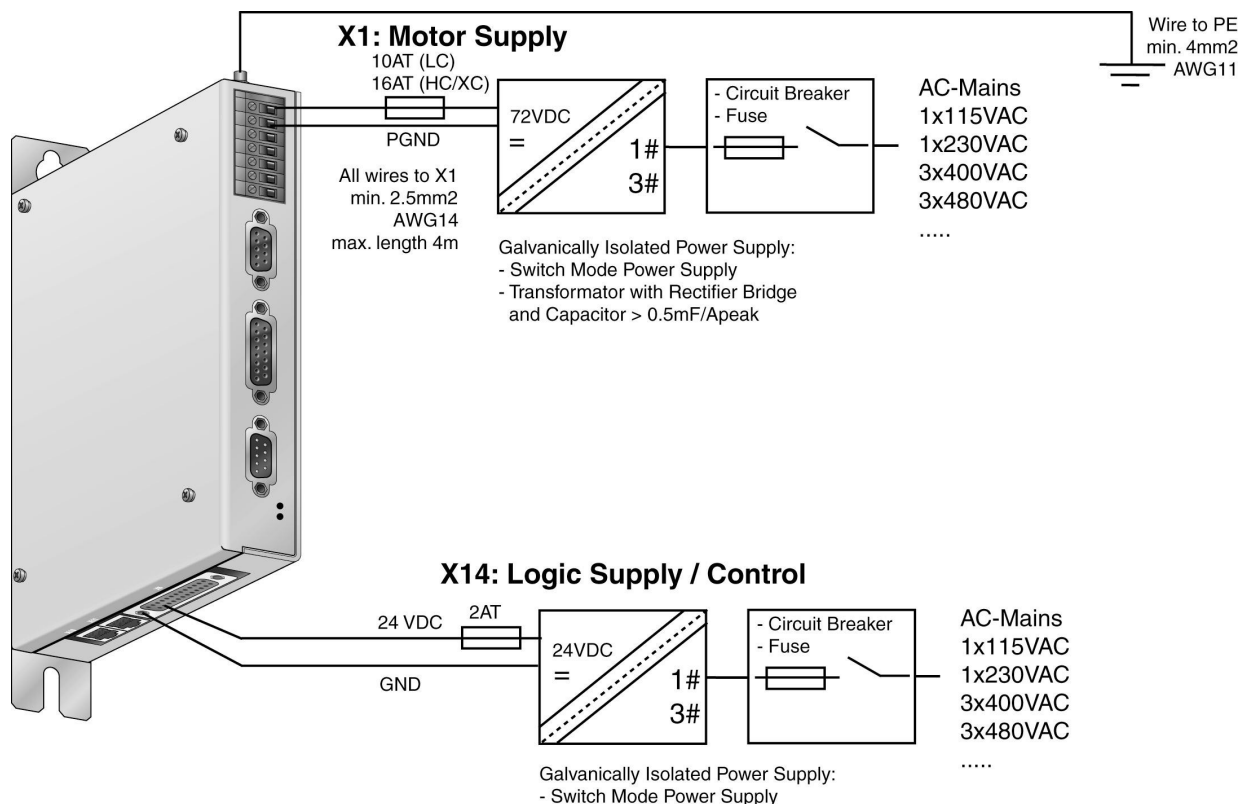
The configuration software LinMot-Talk is free of charge and can be downloaded from our home page.

For fast results see also the quick start guides and configurations for the B1100-PP and B1100-VF controllers:

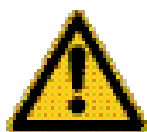
- QuickStartGuide\_B1100-PP.pdf
- QuickStartGuide\_B1100-VF.pdf

This quick start guides are distributed with the LinMot-Talk software.

### Power Supply and Grounding



\*Inside of the B1100 controller the *PWR motor GND* and *PWR signal GND* is connected together and to the GND of the controller housing. It is recommended that the *PWR motor GND* is NOT grounded at another place than inside of the controller to avoid circular currents.



In order to assure a safe and error free operation, and to avoid severe damage to system components, **all system components\* must be well grounded to either a single earth or utility ground.** This includes both LinMot and all other control system components to the same ground bus.



Each system component\* should be tied directly to the ground bus (**star pattern**), rather than daisy chaining from component to component. (LinMot motors are properly grounded through their power cables when connected to LinMot controllers.)




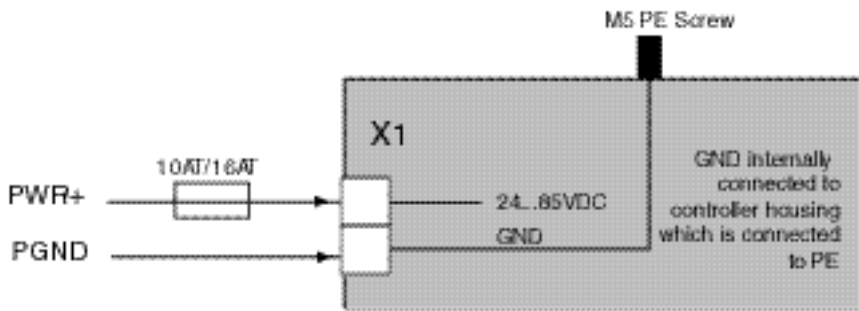
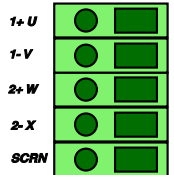
**Power supply connectors must not be connected or disconnected while DC voltage is present.** Do not disconnect system components until all LinMot controllers LEDs have turned off. (Capacitors in the power supply may not fully discharge for several minutes after input voltage has been disconnected). Failure to observe these precautions may result in severe damage to electronic components in LinMot motors and/or controllers.

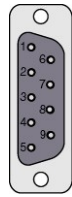


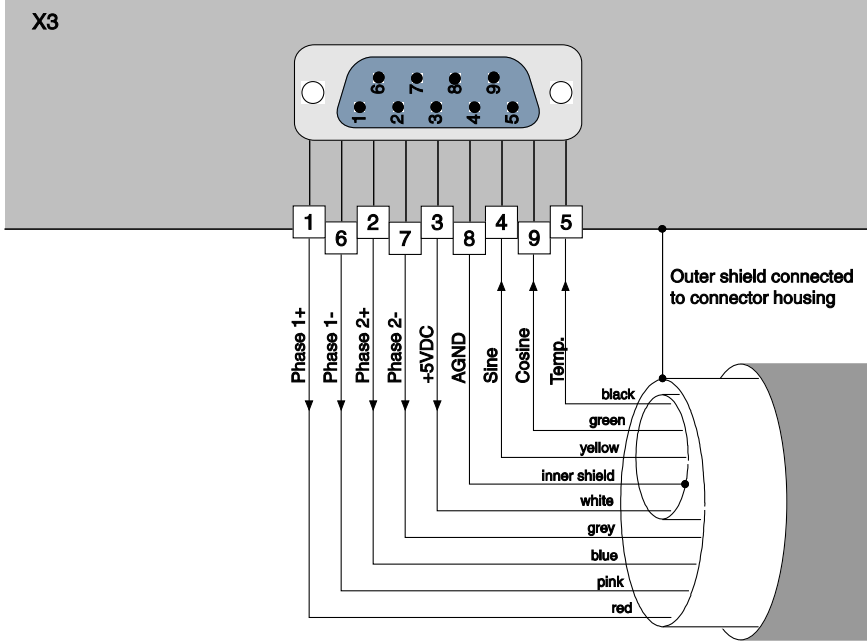



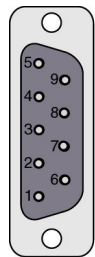
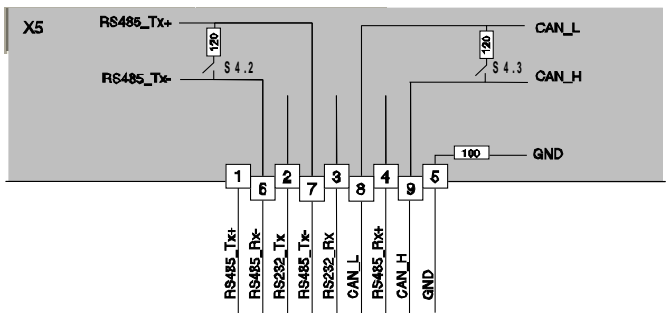
**Do not switch Power Supply DC Voltage.** All power supply switching and E-Stop breaks should be done to the AC supply voltage of the power supply. Failure to observe these precautions may result in severe damage to controller.

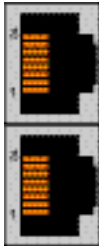
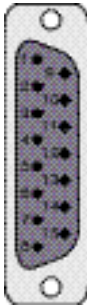


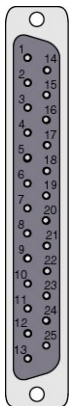
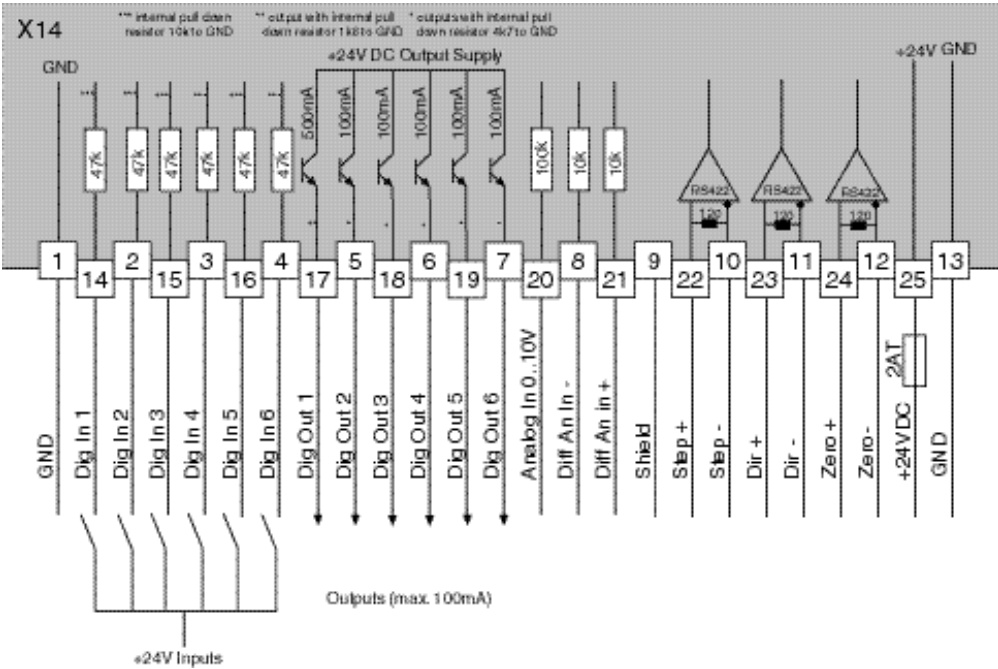
## Description of the connectors / Interfaces

<b>X1:</b>	<b>Motor Supply</b>				
					
Screw Terminals	<p>Motor Supply: 72VDC nominal, 24...85VDC Absolute max. Rating: 72VDC +20%.</p> <p>External Fuse: 10AT for LC (8Apeak), 16AT for HC and XC (15A/25Apeak) servos.</p> <p>If motor supply voltage exceeds 90VDC, the controller will go into error state.</p> <ul style="list-style-type: none"> <li>- Tightening Torque: min 0.4Nm</li> <li>- Screw Thread: M 2,5</li> <li>- Use 60/75°C copper conductors only</li> <li>- Conductor Cross-Section 2.5mm<sup>2</sup> (AWG14) max Length 4m</li> </ul>				
<b>X2:</b>	<b>Motor Phases</b>				
	<table border="0"> <tr> <td data-bbox="391 1220 550 1355">           PH1+ /U            PH1- /V            PH2+ /W            PH2-            SCRN         </td><td data-bbox="550 1176 1029 1355"> <b>LinMot Motor:</b>             Motor Phase 1+    red            Motor Phase 1-    pink            Motor Phase 2+    blue            Motor Phase 2-    grey            Shield         </td><td data-bbox="1029 1176 1412 1355"> <b>3-phase EC-Motor:</b>             Motor Phase U            Motor Phase V            Motor Phase W         </td></tr> </table>		PH1+ /U PH1- /V PH2+ /W PH2- SCRN	<b>LinMot Motor:</b>  Motor Phase 1+    red Motor Phase 1-    pink Motor Phase 2+    blue Motor Phase 2-    grey Shield	<b>3-phase EC-Motor:</b>  Motor Phase U Motor Phase V Motor Phase W
PH1+ /U PH1- /V PH2+ /W PH2- SCRN	<b>LinMot Motor:</b>  Motor Phase 1+    red Motor Phase 1-    pink Motor Phase 2+    blue Motor Phase 2-    grey Shield	<b>3-phase EC-Motor:</b>  Motor Phase U Motor Phase V Motor Phase W			
Screw Terminals	<p>The motor phases are present at X2 and X3. It is recommended to use X2. It is only allowed to use X3 for connecting motor phases if RMS current is below 2A and peak current is below 4A. Never connect motor phases on X2 and X3!</p> <ul style="list-style-type: none"> <li>- Tightening Torque: min 0.4Nm</li> <li>- Screw Thread: M 2,5</li> <li>- Conductor Cross-Section: max. 2.5mm<sup>2</sup></li> <li>- Use 60/75°C copper conductors only</li> </ul>				

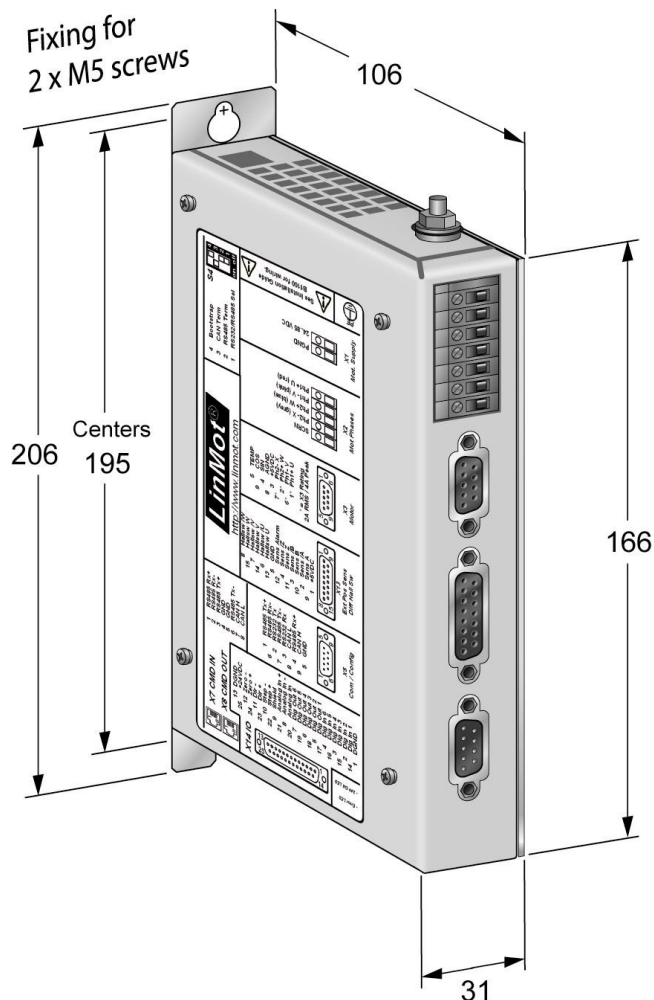
X3:	Motor	
	<b>LinMot Motor:</b>	<b>3-phase EC-Motor:</b>
	<div><div>1</div>Motor Phase 1+</div> <div><div>2</div>Motor Phase 2+</div> <div><div>3</div>+5VDC</div> <div><div>4</div>Sensor Sine</div> <div><div>5</div>Temp. In</div> <div><div>6</div>Motor Phase 1-</div> <div><div>7</div>Motor Phase 2-</div> <div><div>8</div>AGND</div> <div><div>9</div>Sensor Cosine</div> <div>case</div> Shield <div><div>+5VDC (Hall Supply)</div><div>Hall 1</div><div>Hall 3</div><div>AGND (Hall Supply)</div><div>Hall 2</div></div>	
DSUB-9 (f)	<p><u>Note:</u> Use +5V (X3.3) and AGND (X3.8) only for motor internal hall sensor supply (max. 100mA).</p> <p><u>Caution:</u> Do NOT connect AGND (X3.8) to ground or earth! It is only allowed to use X3 for connecting the motor phases if RMS current is below 2A and peak current below 4A.</p>	
Motor Wiring for Phase Currents above 2A RMS 4A peak (recommended general wiring)		
	<div><div><div><div>X2</div><div><div>MEC6</div><div>X-2</div><div>A-2</div><div>A-1</div><div>n-1</div></div><div><div>SHIELD</div><div>PH2-</div><div>PH2+</div><div>PH1-</div><div>PH1+</div></div></div><div><div>Outer shield</div><div>Phase 2- (grey)</div><div>Phase 2+ (blue)</div><div>Phase 1- (pink)</div><div>Phase 1+ (red)</div></div></div><div><div><div>X3</div><div><div>1</div><div>2</div><div>3</div><div>4</div><div>5</div></div><div><div>6</div><div>7</div><div>8</div><div>9</div></div></div><div><div>Caution:</div><div>Do not</div><div>connect</div><div>X3.1/2/6/7</div></div><div><div>+5VDC</div><div>AGND</div><div>Sine</div><div>Cosine</div><div>Temp.</div></div><div><div>black</div><div>green</div><div>yellow</div><div>Inner shield</div><div>white</div><div>red</div><div>pink</div><div>blue</div><div>grey</div></div></div></div>	
	<p><u>Important:</u> If motor phase current exceeds <math>2A_{RMS}</math> or <math>4A_{peak}</math>, motor phases must be wired to X2.</p>	

Motor wiring for Phase Currents below 2A RMS 4A peak			
	<div><div>X3</div><div></div></div>		
	<p><u>Important:</u> Motor phases may only be connected to X3 if RMS current is below 2A and peak current is below 4A.</p>		
LED:	State Display		
Error   24V OK	Green Red	24V Logic Supply OK Error (Fatal Error blinking)	
S4:	Bus Termination		
	S4	Switch 4: Bootstrap Switch 3: Termination CAN on/off Switch 2: Termination RS485 on/off Switch 1: RS232 (switch "off" / RS485 "on"). Selection for RS232 or RS485 Factory settings: Switch 3 "on", all other switches "off"	
X5:	COM		
	<div><div>1 2 3 4 5 6 7 8 9 case</div><div>RS485_Tx+ RS232_Tx RS232_Rx RS485_Rx+ GND RS485_Rx- RS485_Tx- CAN_L CAN_H Shield</div><div>Y A B Z</div></div>	<div><div>X5</div><div></div></div>	
DSUB-9 (m)	RS232: Configuration on all controllers: use 1:1 connection cable to PC		

X7 - X8		RS485/CAN	
	<div><div>1</div><div>2</div><div>3</div><div>4</div><div>5</div><div>6</div><div>7</div><div>8</div><div>case</div></div>	<div><div>RS485_Rx+</div><div>RS485_Rx-</div><div>RS485_Tx+</div><div>GND</div><div>GND</div><div>RS485_Tx-</div><div>CAN_H</div><div>CAN_L</div><div>Shield</div></div>	<div><div>A</div><div>B</div><div>Y</div><div></div><div></div><div>Z</div><div></div><div></div><div></div></div>
RJ-45	Use twisted pair (1-2, 3-6, 4-5, 7-8) cable for wiring. The built in CAN and RS485 terminations can be activated by S4.2 and S4.3. X7 is internally connected to X8 (1:1 connection)		
X13:		External Position Sensor Differential Hall Switches	
	<div><div>1</div><div>9</div><div>2</div><div>10</div><div>3</div><div>11</div><div>4</div><div>12</div><div>5</div><div>13</div><div>6</div><div>14</div><div>7</div><div>15</div><div>8</div><div>case</div></div>	<div><div>+5V DC</div><div>A+</div><div>A-</div><div>B+</div><div>B-</div><div>Z+</div><div>Z-</div><div>Encoder Alarm</div><div>GND</div><div>U+</div><div>U-</div><div>V+</div><div>V-</div><div>W+</div><div>W-</div><div>Shield</div></div>	
DSUB-15 (f)	<div><div><div>Position Encoder Inputs:</div><div>RS422</div><div>Max Input Frequency: 2MHz, 4 M counts/s with quadrature decoding, 240ns edge separation</div></div><div><div>Encoder Simulation Outputs:</div><div>RS422</div><div>Max Output Frequency: 2.5MHz, 5 M counts/s with quadrature decoding, 200ns edge separation</div></div><div><div>Differential Hall Switch Inputs:</div><div>RS422</div><div>Input Frequency: &lt;1kHz</div></div><div><div>Enc. Alarm In:</div><div>5V / 1mA</div></div><div><div>Sensor Supply:</div><div>5VDC max 100mA</div></div></div>		

X14:	24VDC Supply and IOs
	 <p><b>X14</b></p> <p>*** internal pull down resistor 10k to GND    ** output with internal pull down resistor 1k to GND    * output with internal pull down resistor 4k7 to GND</p> <p><b>+24V DC Output Supply</b></p> <p>Pin 1: GND Pin 2: Dig In 1 Pin 3: Dig In 2 Pin 4: Dig In 3 Pin 5: Dig In 4 Pin 6: Dig In 5 Pin 7: Dig In 6 Pin 8: Dig Out 1 Pin 9: Dig Out 2 Pin 10: Dig Out 3 Pin 11: Dig Out 4 Pin 12: Dig Out 5 Pin 13: Dig Out 6 Pin 14: Analog In 0..10V Pin 15: Diff An In - Pin 16: Diff An In + Pin 17: Shield Pin 18: Step + Pin 19: Step - Pin 20: Dir + Pin 21: Dir - Pin 22: Zero + Pin 23: Zero - Pin 24: +24VDC Pin 25: GND</p> <p>Outputs (max. 100mA)</p> <p>+24V Inputs</p>
<p>DSUB-25 (f)</p>	<p><b>Logic Supply:</b> Switch Mode Power Supply: 24VDC (22...26VDC) External Fuse: 2AT</p> <p><b>All Digital Inputs:</b> Direct interfacing to digital 24VDC PLC outputs. Input Current: 1mA Logic Levels: Low Level: guaranteed: -5 to 5VDC, typical &lt; 8VDC High Level guaranteed: 20...30VDC, typical &gt; 16VDC Sample Rate: 400us</p> <p><b>All Digital Outputs:</b> Short circuit and overload protected high side switches. Voltage: 24VDC Update Rate: 400us Max. Current: 100mA/500mA (X14.17) Peak Current: 370mA/1100mA (X14.17) will shut down if exceeds Outputs may directly drive inductive loads. Do not connect any capacity because of the peak current!</p> <p><b>Analog Input on X14.20:</b> Range: 0V...+10V 10Bit ADC Sample Rate: 400us</p> <p><b>Differential Analog Input on X14.8 X14.21 X14.9 Shield:</b> Range: -10V...+10V 10Bit ADC Sample Rate: 400us</p> <p><b>Differential Step Dir Zero:</b> Indexer Inputs: RS422, Max. Input Frequency: 2MHz, 4 M counts/s with quadrature decoding, 240ns edge separation</p>

### Physical Dimension



<b>B1100 Single axes controller</b>		
Width	mm (in)	31 (1.3)
Height	mm (in)	166 (6.6)
Height with fixings	mm (in)	206 (8.1)
Depth	mm (in)	106 (4.2)
Weight	g (lb)	700 (1.6)
Case	IP	20
Storage Temperature	°C	-25...40
Transport Temperature	°C	-25...70
Operating Temperature	°C	0...40 at rated data 40...50 with power derating
Relative humidity		95% (non-condensing)
Max. Case Temperature	°C	70
Max. Power Dissipation	W	30
Distance between Controllers	mm (in)	20 (0.8) horizontal 50 (2) vertical

( ) dimensions in inch

## **Power Supply Requirement**

### **Power Supply motor**

The calculation of the needed power for the motor supply is depending on the application and the used motor. The nominal supply voltage is 72 VDC. The possible range is from 24 to 85 VDC.



**ATTENTION:** The motor supply can rise up to 95 VDC when braking. This means that everything connected to that power supply needs a voltage rating of 100 VDC. (Additional capacitors, etc...)



To provide short circuit power limitation, it is required to use an external fuse (10AT for blank labeled (LC) and 16AT for HC and XC labeled controllers).

Recommended Power supplies:

Item	Description	Art. No.
T01-72/420	72VDC, 15A peak, 420VA, 3x400VAC	0150-1966
T01-72/420-US	72VDC, 15A peak, 420VA, 3x230VAC	0150-1967
T01-72/900	72VDC, 30A peak, 900VA, 3x400VAC	0150-1842
T01-72/900-US	72VDC, 30A peak, 900VA, 3x230VAC	0150-1843
T01-72/1500	72VDC, 2x30A peak, 1500VA, 3x400VAC	0150-1844
T01-72/1500-US	72VDC, 2x30A peak, 1500VA, 3x230VAC	0150-1845
S01-72/500	72VDC, 500W, 750W peak, 1x100..120VAC/200..240VAC	0150-1874
S01-72/1000	72VDC, 1000W, 2000W peak, 3x380..500VAC	0150-1872

### **Power Supply signal**

The logic supply needs a regulated power supply of a nominal voltage of 24 VDC. The voltage must be between 22 and 26 VDC.

Current Consumption: Min. 200mA (no load on the outputs)  
 Typ. 0.5A (all 6 outputs "on" with 50mA load and /Break with no load)  
 Max. 1.2A (all 6 outputs "on" with 100mA load and /Break with 0.5A load)




To limit the power in case of malfunction, it is required to use an external fuse (2AT).

## **Ordering Information**

<b>Servo Controller</b>	<b>Description</b>	<b>Art. No.</b>
B1100-GP	General Purpose Controller 72VDC/8A	0150-1737
B1100-GP-HC	General Purpose Controller 72VDC/15A	0150-1738
B1100-GP-XC	General Purpose Controller 72VDC/25A	0150-1741
B1100-PP	Point to Point Controller 72VDC/8A	0150-1735
B1100-PP-HC	Point to Point Controller 72VDC/15A	0150-1736
B1100-PP-XC	Point to Point Controller 72VDC/25A	0150-1740
B1100-VF	Current Command Controller 72VDC/8A	0150-1685
B1100-VF-HC	Current Command Controller 72VDC/15A	0150-1686
B1100-VF-XC	Current Command Controller 72VDC/25A	0150-1739

## **International Certifications**

<b>Certifications</b>	
 Europe	See chapter Declaration of Conformity CE-Marking“



## **Declaration of Conformity CE-Marking**

Manufacturer: NTI AG  
 LinMot®  
 Haerdlistrasse 15  
 8957 Spreitenbach  
 Switzerland  
 Tel.: +41 (0)56 419 91 91  
 Fax: +41 (0)56 419 91 92

Products: LinMot® Controllers

Type	Art.-No.	Type	Art.-No.	Type	Art.-No.
B1100-GP	0150-1737	B1100-VF	0150-1685		
B1100-GP-HC	0150-1738	B1100-VF-HC	0150-1686		
B1100-GP-XC	0150-1741	B1100-VF-XC	0150-1739		
B1100-PP	0150-1735				
B1100-PP-HC	0150-1736				
B1100-PP-XC	0150-1740				

The product must be mounted and used in strict accordance with the installation instruction contained within the User's Manual, a copy of which may be obtained from NTI Ltd.

I declare that as the authorized representative, the above information in relation to the supply/manufacture of this product is in conformity with the stated standards and other related documents in compliance with the protection requirements of the EMC Directive (89/336/EEC) and is marked in accordance with the CE Marking Directive (93/68/EEC).

Standards Complied with:

EN 61000-6-2			Immunity for industrial environment
	EN 61000-4-2	Class B	Electrostatic discharge immunity (ESD)
	EN 61000-4-3	Class A	Radiated electromagnetic field immunity
	EN 61000-4-4	Class B	Fast transients / burst immunity (EFT)
	EN 61000-4-5	Class B	Slow transients immunity (Surges)
	EN 61000-4-6	Class A	Conducted radio frequency immunity
EN 61000-6-4			Emission for industrial environment
	EN 55022	Class A	Radiated Emission

Company  
 NTI Ltd.

Zurich, September 20, 2007



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 R. Rohner / CEO NTI AG

## Contact Addresses

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**LinMot, Inc.**

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Please visit <http://www.linmot.com/> to find the distribution near you.

Smart solutions are...

